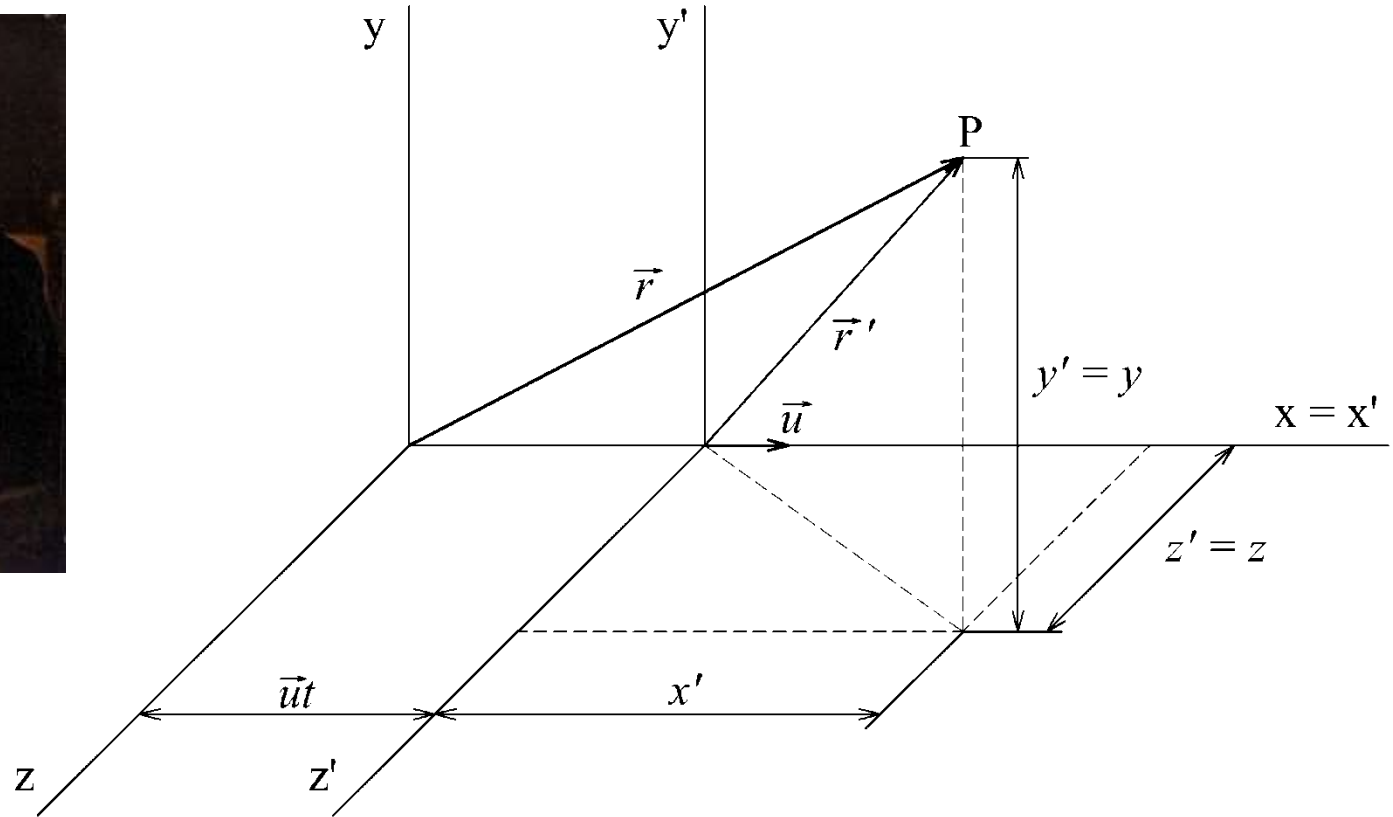


# Dynamika



# Galileova transformace



# Zákon setrvačnosti

ISS

## Zákon síly

$$\vec{F} = m\vec{a} \quad v \ll c \quad m \neq m(t)$$

$$\vec{F} = \frac{d\vec{p}}{dt}$$

hybnost  $\vec{p} = m\vec{v}$

$$\vec{F} = m \frac{d^2\vec{r}}{dt^2}$$

$$\vec{F} = m\vec{a} = m \frac{d\vec{v}}{dt} = \frac{d}{dt}(m\vec{v}) = \frac{d\vec{p}}{dt}$$

Pohybová rovnice

impulz síly  $\vec{I} = \int_{t_1}^{t_2} \vec{F} dt$

$$\vec{I} = \int_{t_1}^{t_2} \vec{F} dt = \int_{t_1}^{t_2} \frac{d\vec{p}}{dt} dt = \int_{\vec{p}_1}^{\vec{p}_2} d\vec{p} = \vec{p}_2 - \vec{p}_1 = m\vec{v}_2 - m\vec{v}_1$$

## 2. Newtonův pohybový zákon

## Zákon akce a reakce

$$\vec{F}_{12} = \frac{d\vec{p}_1}{dt} \quad \vec{F}_{12} = -\vec{F}_{21} \quad \vec{F}_{21} = \frac{d\vec{p}_2}{dt}$$

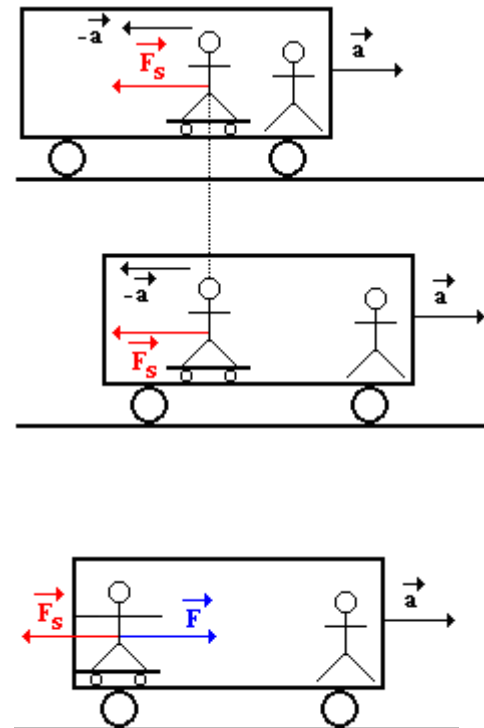
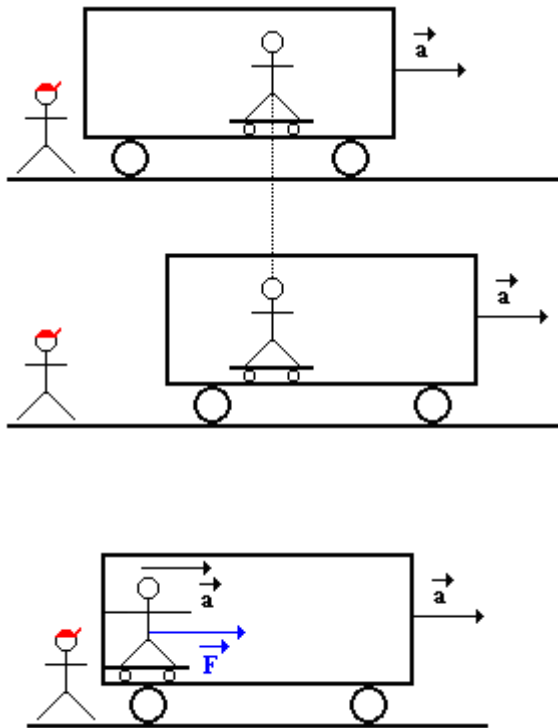
$$0 = \frac{d\vec{p}_1}{dt} + \frac{d\vec{p}_2}{dt} = \frac{d}{dt}(\vec{p}_1 + \vec{p}_2)$$

$$\vec{p}_1 + \vec{p}_2 = \overrightarrow{\text{konst}}$$

**zákon zachování  
hybnosti (ZZH)**

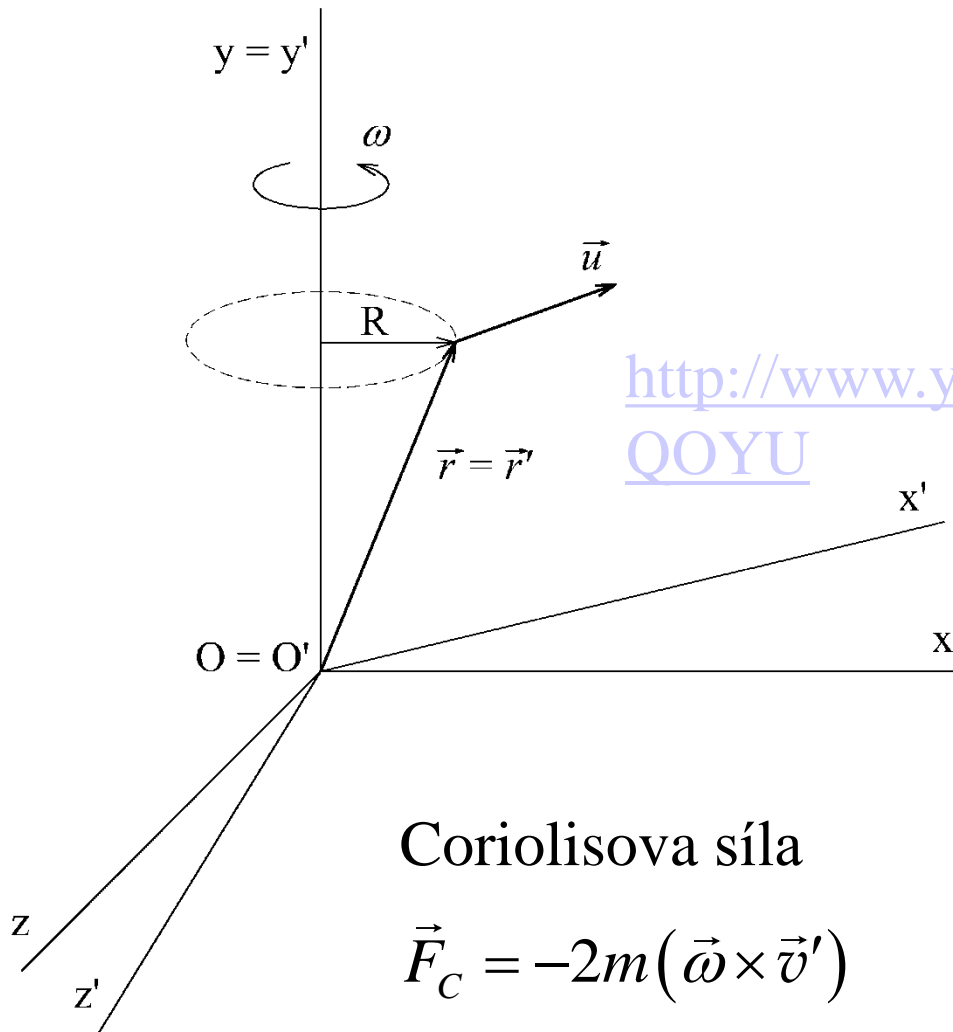
<http://physics.fme.vutbr.cz/ufi.php?Action=0&Id=83>

# Neinerciální souřadnicová soustava



<http://fyzika.jreichl.com/main.article/view/40-neinercialni-vztazne-soustavy>

# Neinerciální souřadnicová soustava



Coriolisova síla

$$\vec{F}_C = -2m(\vec{\omega} \times \vec{v}')$$

$$\vec{r} = \vec{r}' (t = 0)$$

$$\vec{v} = \vec{v}' + \vec{u}$$

$$\vec{u} = \vec{\omega} \times \vec{r}$$

[http://www.youtube.com/watch?v=mcPs\\_OdQOYU](http://www.youtube.com/watch?v=mcPs_OdQOYU)

$$\vec{F}' = m\vec{a}' = m\vec{a} + \vec{F}^* + \vec{F}_C + \vec{F}_o$$

$$\vec{F}_o = -m[\vec{\omega} \times (\vec{\omega} \times \vec{r}')] ]$$

$$\vec{F}' = \vec{F} + \vec{F}_s$$

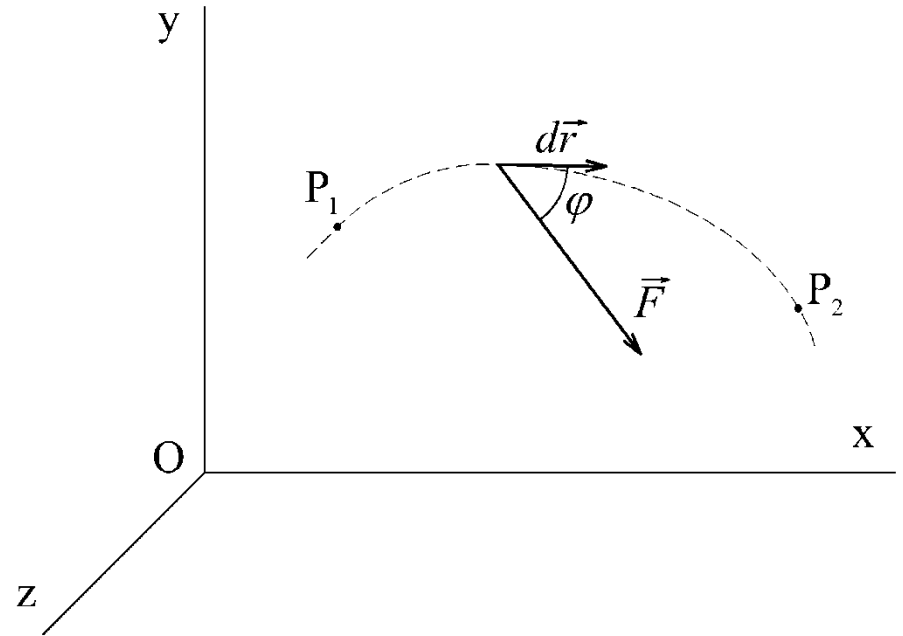


[http://cs.wikipedia.org/wiki/Soubor:Low\\_pressure\\_system\\_over\\_Iceland.jpg](http://cs.wikipedia.org/wiki/Soubor:Low_pressure_system_over_Iceland.jpg)

# Práce a energie

$$dA = \vec{F} \cdot d\vec{r}$$

$$A = \int_{P_1}^{P_2} \vec{F} \cdot d\vec{r} = \int_{P_1}^{P_2} F dr \cos \varphi$$



$$\begin{aligned} A &= \int_{P_1}^{P_2} \vec{F} \cdot d\vec{r} = m \int_{P_1}^{P_2} \frac{d\vec{v}}{dt} \cdot d\vec{r} = m \int_{P_1}^{P_2} \left[ \left( \frac{d\vec{v}}{dt} \right)_t + \left( \frac{d\vec{v}}{dt} \right)_n \right] \cdot d\vec{r} = m \int_{P_1}^{P_2} \left( \frac{d\vec{v}}{dt} \right)_t \cdot d\vec{r} \\ &= m \int_{P_1}^{P_2} \left( \frac{dv}{dt} \right) dr = m \int_{t_1}^{t_2} \left( \frac{dv}{dt} \right) \frac{dr}{dt} dt = m \int_{t_1}^{t_2} \left( \frac{dv}{dt} \right) v dt = m \int_{v_1}^{v_2} v dv \end{aligned}$$

$$A = \frac{1}{2} m v_2^2 - \frac{1}{2} m v_1^2$$

**kinetická energie**

$$W_k = \frac{1}{2} m v^2$$



# Zákon zachování mechanické energie

$$A = \int_{P_1}^{P_2} \vec{F} \cdot d\vec{r} = -\Delta W_p = \Delta W_k$$

$$\Delta W_k + \Delta W_p = \Delta(W_k + W_p) = 0$$

$$W_k + W_p = \text{konst}$$

# Výkon

$$P = \frac{dA}{dt}$$

okamžitý výkon

$$A = \int_{t_1}^{t_2} P dt$$

$$P = \frac{dA}{dt} = \vec{F} \cdot \frac{d\vec{r}}{dt} = \vec{F} \cdot \vec{v}$$

$$\eta = \frac{P_V}{P_P} \quad \text{účinnost}$$